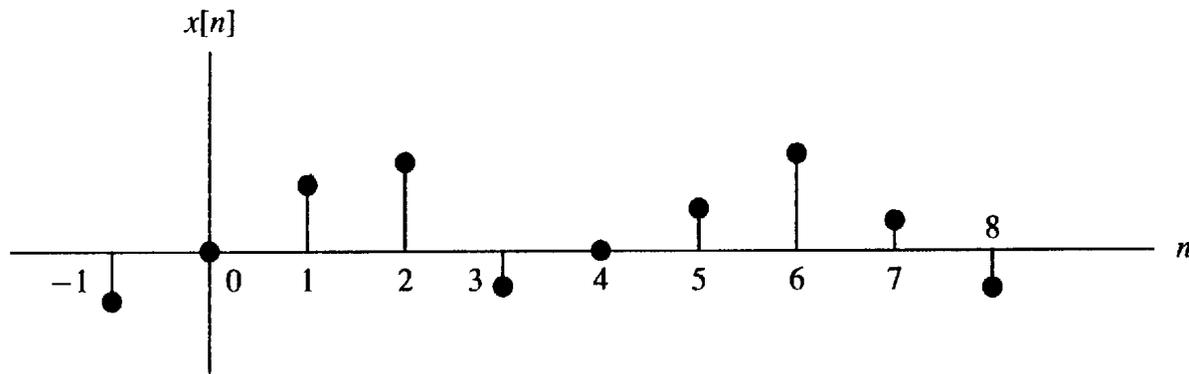


RANDOM SIGNALS/SEQUENCES



$\dots, x[-1], x[0], x[1], \dots$ are random variables

- Sequence is called a *random signal* or *time series*.
- Underlying model is a *random process* or *stochastic process*.

NOTES ABOUT RANDOM SIGNALS

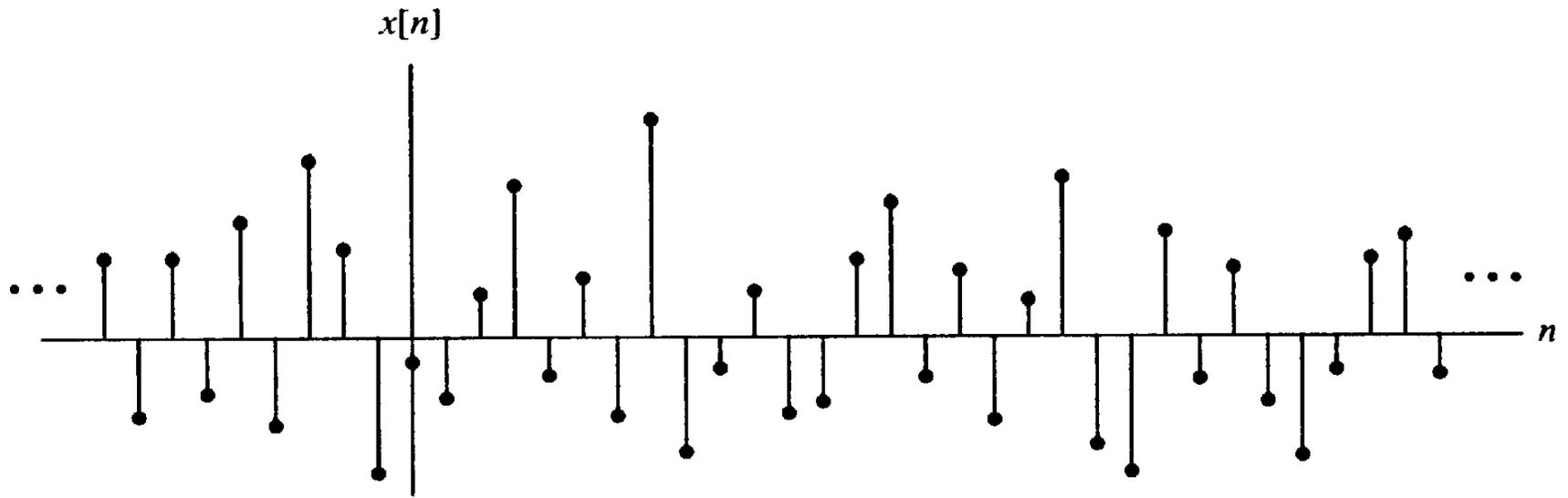
- Random signals generally have *infinite* energy:

$$\mathcal{E} \left\{ \sum_{n=-\infty}^{\infty} |x[n]|^2 \right\} = \sum_{n=-\infty}^{\infty} \mathcal{E} \{ |x[n]|^2 \} = \infty$$

- Random signals may be *predictable*.

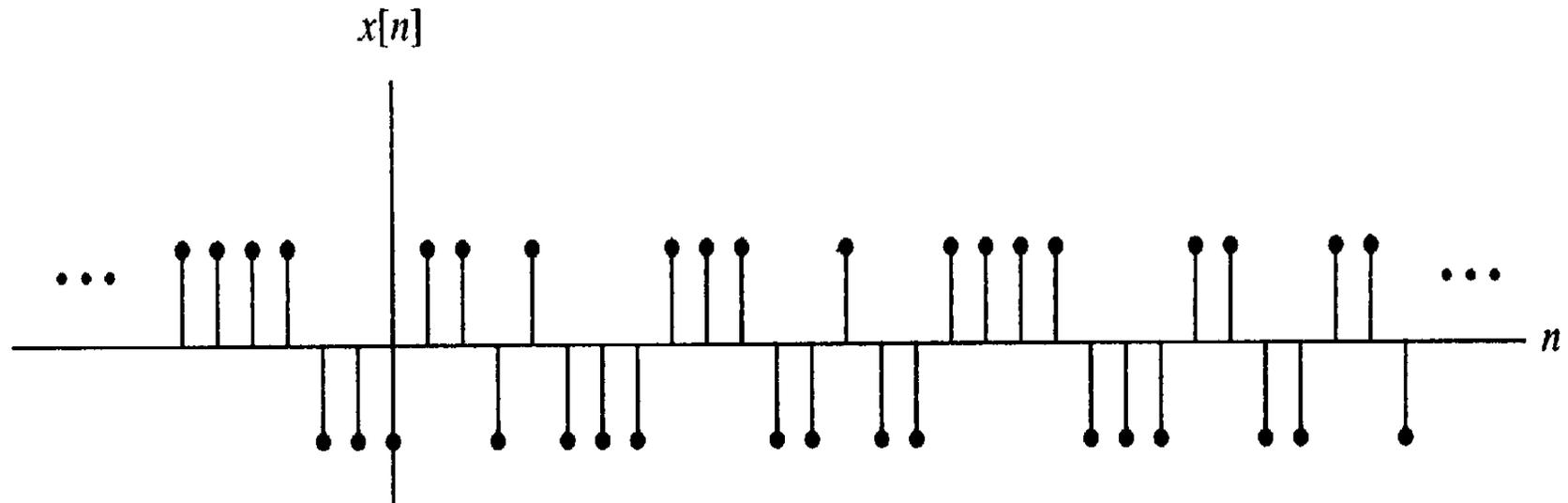
RANDOM SIGNAL EXAMPLES

NOISE



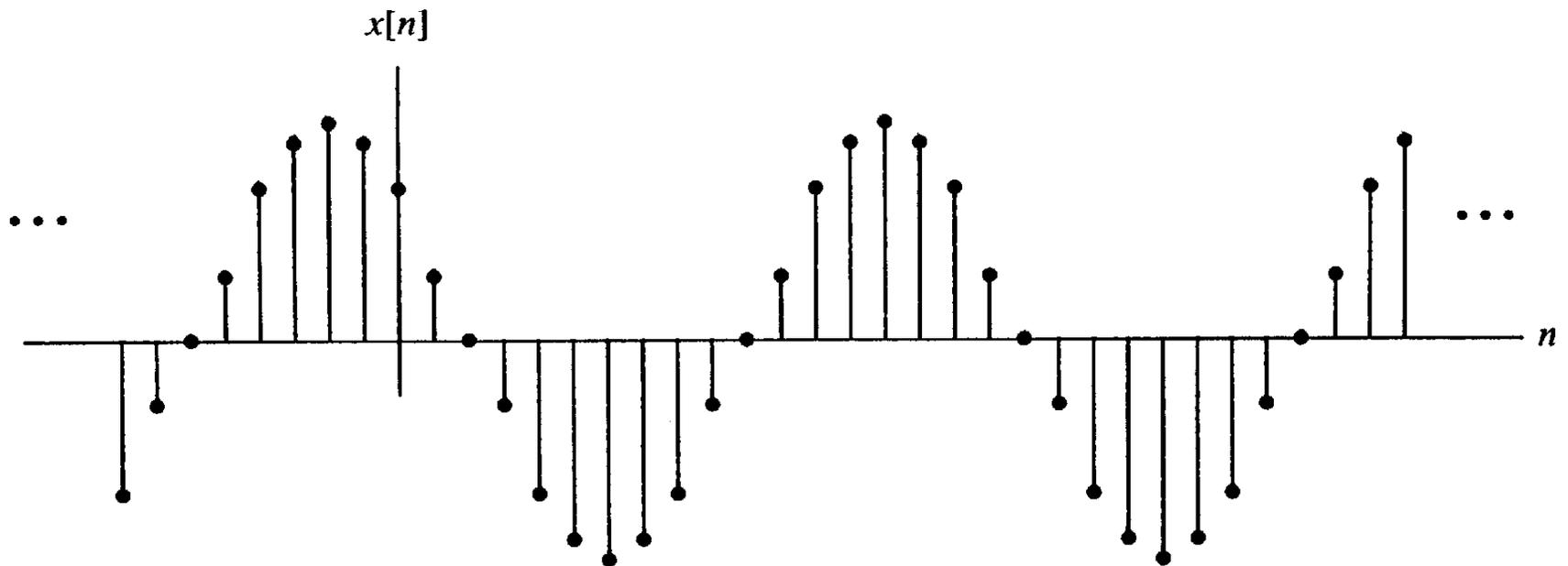
RANDOM SIGNAL EXAMPLES (cont'd.)

BINARY CODED DATA



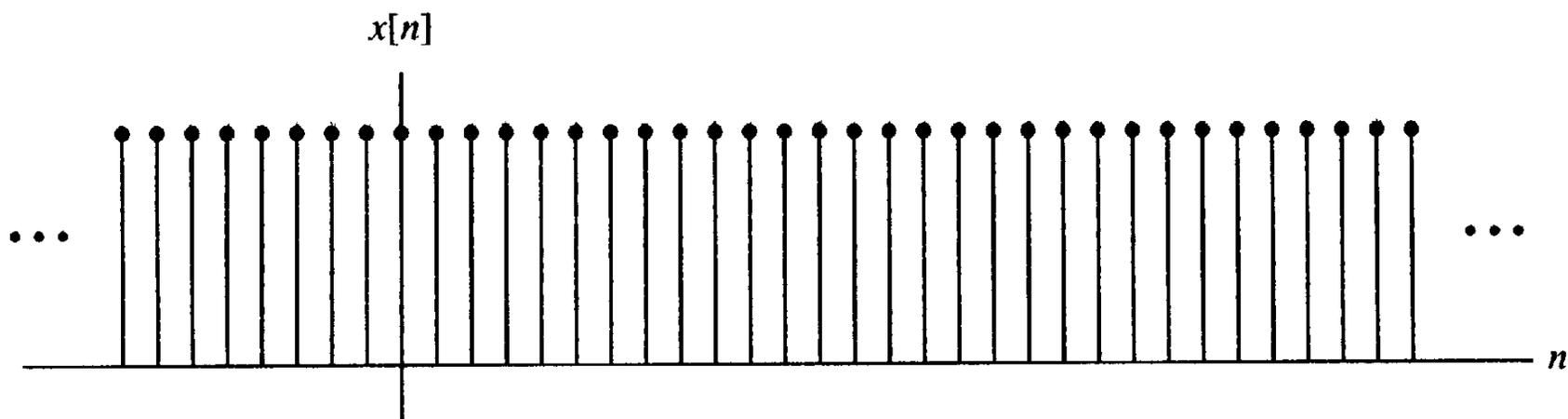
RANDOM SIGNAL EXAMPLES (cont'd.)

RANDOM SINUSOID



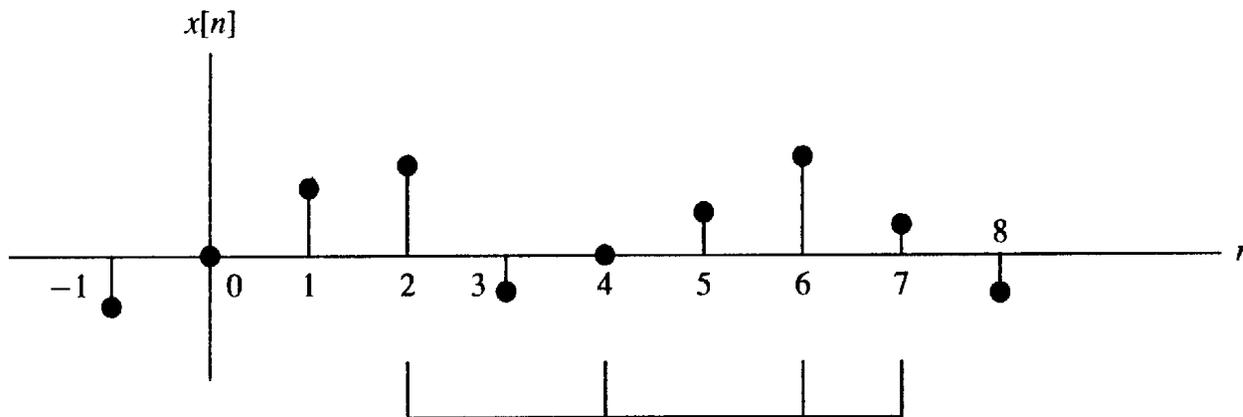
RANDOM SIGNAL EXAMPLES (cont'd.)

BATTERY VOLTAGE



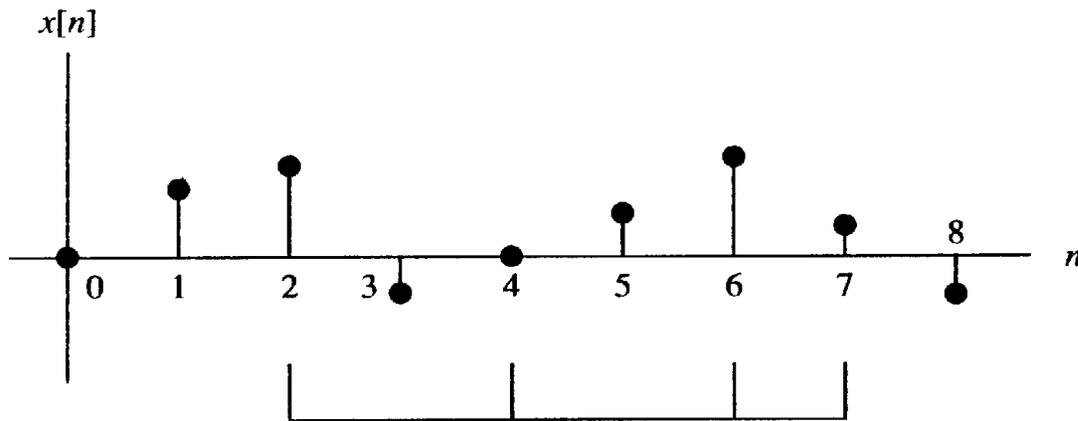
STATISTICAL CHARACTERIZATION OF RANDOM SIGNALS

- Random signals are characterized by the joint distribution or joint density for the samples.



STATISTICAL CHARACTERIZATION (cont'd.)

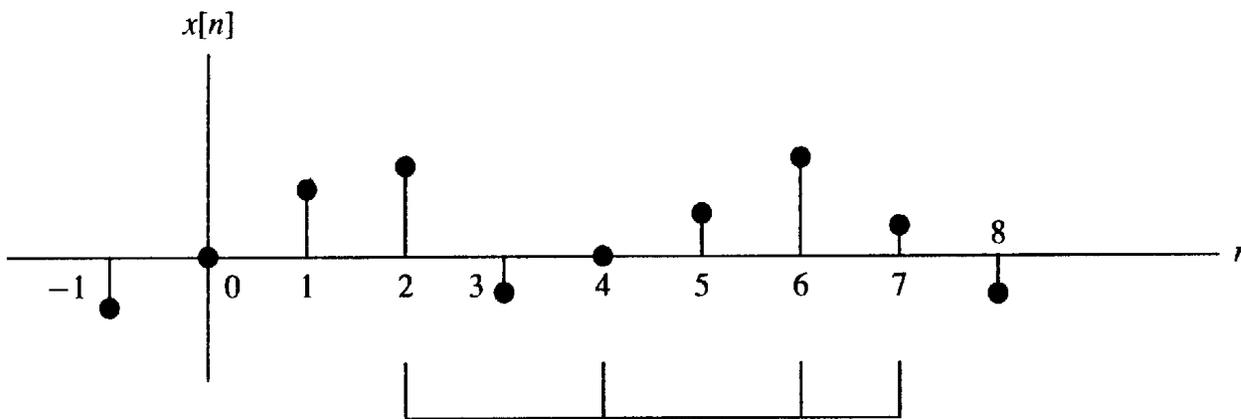
- It is necessary and sufficient to consider just blocks of contiguous samples, represented as random vectors:



$$\mathbf{x} = \begin{bmatrix} x[n] \\ x[n-1] \\ \vdots \\ x[n+N-1] \end{bmatrix}$$

STATIONARITY (STRICT SENSE)

A random process is stationary if any joint density or distribution function depends only on the spacing between samples and not on where in the sequence the samples occur.



$$f_{x[2]x[4]x[6]x[7]} = f_{x[1]x[3]x[5]x[6]} = f_{x[-1]x[1]x[3]x[4]} = \dots$$

STATIONARITY (cont'd.)

- Stationarity requires that all moments

$$\mathcal{E} \left\{ x^{k_0}[n_0] \cdot x^{k_1}[n_1] \dots x^{k_L}[n_L] \right\}$$

depend only on the intersample spacing.

Equivalently:

$$\mathcal{E} \left\{ x^{k_0}[n] \cdot x^{k_1}[n + l_1] \dots x^{k_L}[n + l_L] \right\}$$

is not a function of n .

ENSEMBLE CONCEPT

- A random variable arises as the outcome of an experiment.

Example: Roll of a die

- A random sequence is also the outcome of an experiment.

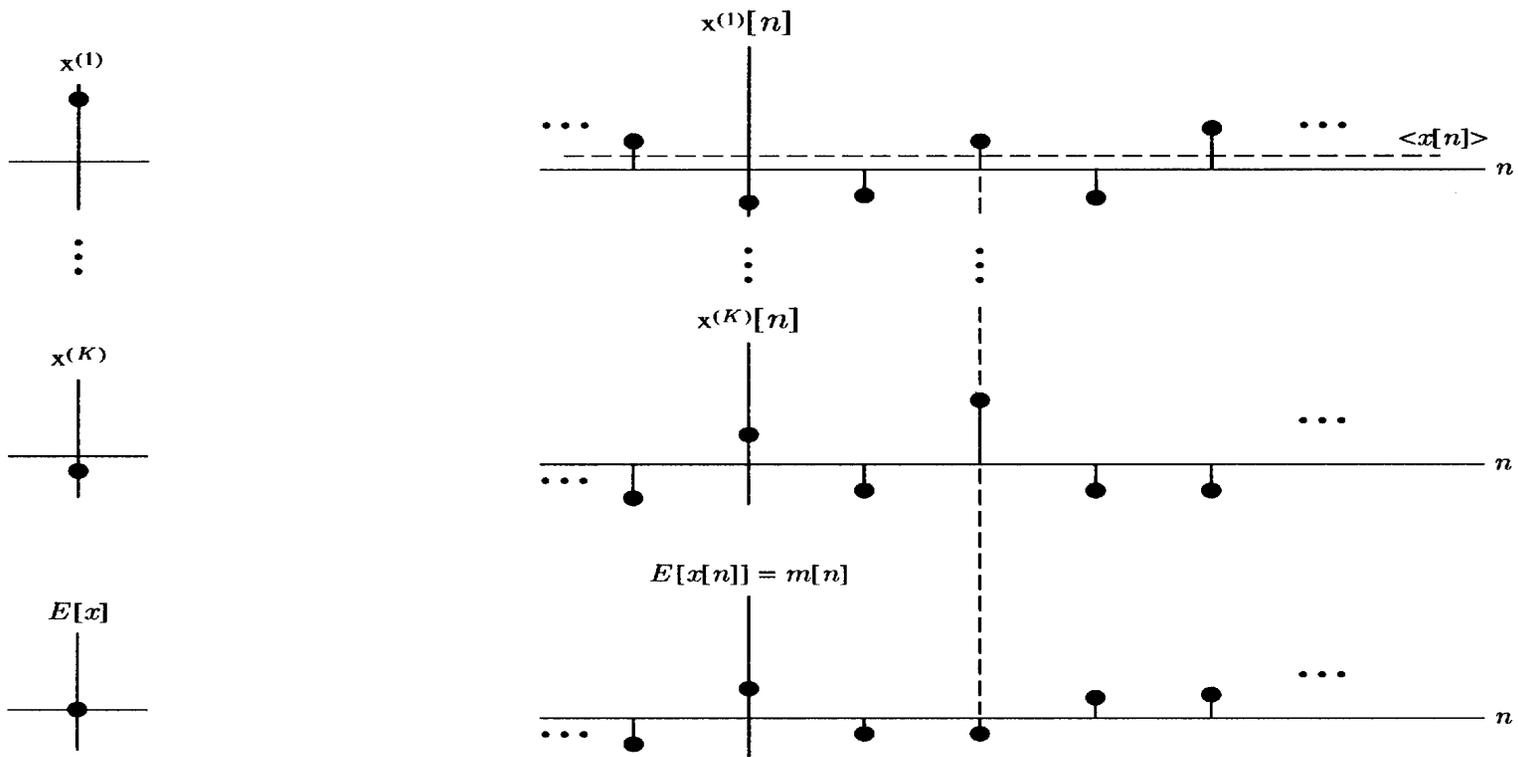
Example: Record of binary data

- The collection of all possible outcomes is called an ensemble.

ILLUSTRATION OF ENSEMBLE

RANDOM VARIABLE

RANDOM PROCESS



ENSEMBLE AVERAGES

RANDOM VARIABLE

$$m_x = \mathcal{E}\{x\} = \int_{-\infty}^{\infty} x f_x(x) dx \approx \frac{1}{K} \sum_{k=1}^K x^{(k)}$$

RANDOM PROCESS

$$m_x[n] = \mathcal{E}\{x[n]\} = \int_{-\infty}^{\infty} x_n f_{x[n]}(x_n) dx_n \approx \frac{1}{K} \sum_{k=1}^K x^{(k)}[n]$$

- As $K \rightarrow \infty$ statistical expectation is equivalent to averaging down the ensemble.

SIGNAL AVERAGES

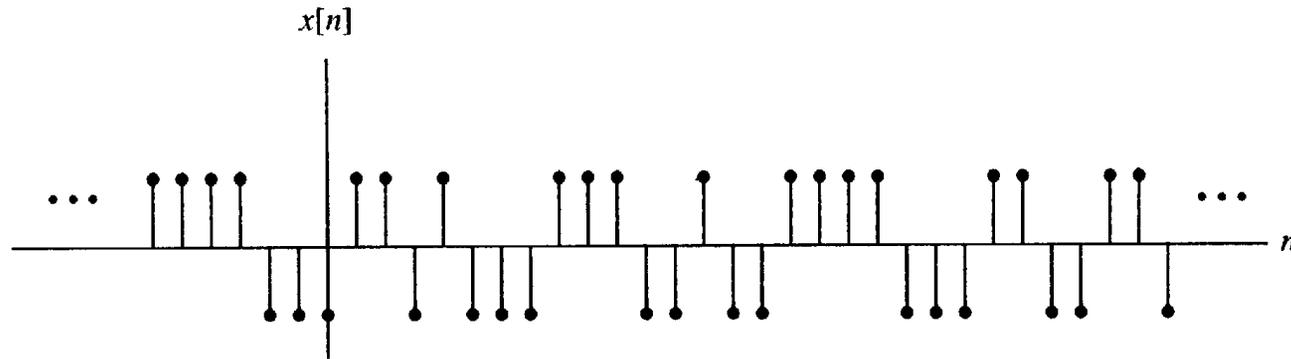
- For a single experimental outcome (ensemble member):

$$\langle x[n] \rangle \stackrel{\text{def}}{=} \lim_{M \rightarrow \infty} \frac{1}{2M+1} \sum_{n=-M}^M x[n]$$

- A stationary process is ergodic if signal averages are equal to ensemble averages with probability 1:

$$\begin{aligned} \langle x^{k_0}[n] x^{k_1}[n+l_1] \cdots x^{k_L}[n+l_L] \rangle \\ \doteq \mathcal{E} \left\{ x^{k_0}[n] x^{k_1}[n+l_1] \cdots x^{k_L}[n+l_L] \right\} \end{aligned}$$

BERNOULLI PROCESS



Samples are independent and

$$x[n] = \begin{cases} +1 & \text{with probability } P \\ -1 & \text{with probability } 1 - P \end{cases}$$

- For $P = \frac{1}{2}$ the process is called binary white noise.

BERNOULLI PROCESS

PROBABILISTIC DESCRIPTION

One can write the probability of any subsequence explicitly.

Example:

$$\begin{aligned} \Pr[x[0] = 1, x[1] = 1, x[2] = -1, x[3] = 1, x[4] = -1] \\ = P \cdot P \cdot (1 - P) \cdot P \cdot (1 - P) = P^3(1 - P)^2 \end{aligned}$$

- Since the probability of any sequence is independent of the starting point, the process is *stationary*.

MOMENTS OF THE BERNOULLI PROCESS

MEAN

$$\mathcal{E}\{x[n]\} = P \cdot (+1) + (1 - P)(-1) = 2P - 1$$

VARIANCE

$$\begin{aligned}\text{Var}[x[n]] &= \mathcal{E}\{(x[n])^2\} - (\mathcal{E}\{x[n]\})^2 \\ &= P \cdot (+1)^2 + (1 - P) \cdot (-1)^2 - (2P - 1)^2 \\ &= 1 - (2P - 1)^2 = 4P(1 - P)\end{aligned}$$

BERNOULLI PROCESS

SUMMARY

	Bernoulli Process	Binary White Noise
Distribution	$\Pr[x[n] = +1] = P$ $\Pr[x[n] = -1] = 1 - P$	$\Pr[x[n] = +1] = \frac{1}{2}$ $\Pr[x[n] = -1] = \frac{1}{2}$
Mean	$2P - 1$	0
Variance	$4P(1 - P)$	1

RANDOM WALK

Consider $x[n] = \sum_{k=-\infty}^n \xi[k]$ where $\xi[k]$ a Bernoulli process.

- $x[n]$ can take on any integer values.
- By Central Limit Theorem $x[n]$ is Gaussian (∞ variance).
- $x[n]$ has *independent increments*:

$$(x[1] - x[0]) ; (x[2] - x[1]) ; \dots ; (x[k] - x[k - 1])$$

\Rightarrow Events defined on non-overlapping time intervals are independent.

RANDOM WALK (cont'd.)

The process $x_{n_0}[n] = x[n] - x[n_0]$; $n > n_0$ is called a random walk:

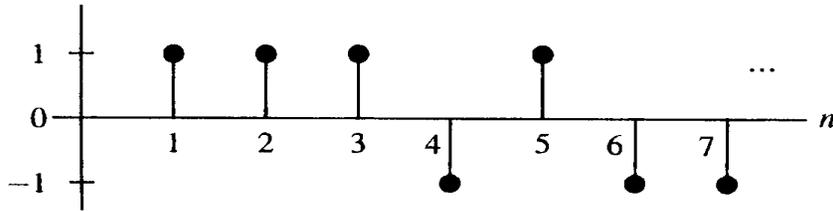
$$x_{n_0}[n] = \sum_{k=n_0+1}^n \xi[k] \quad (n_0 \text{ fixed})$$

Usually $n_0 = 0$ or $n_0 = 1$

- For $P = \frac{1}{2}$ ($\xi[k]$ binary white noise) the random walk is called a discrete Wiener process.

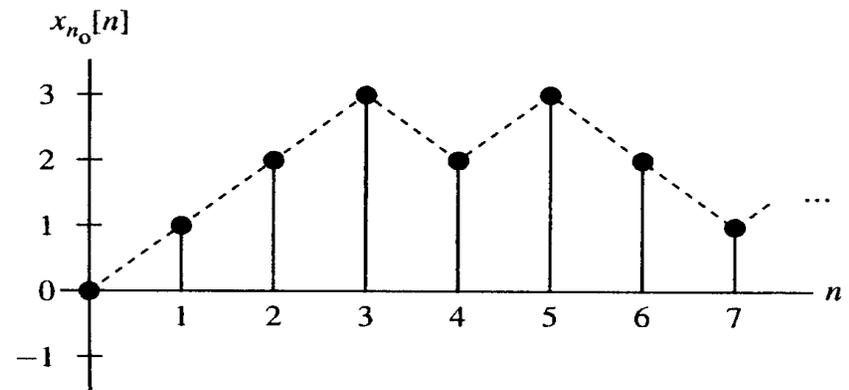
EXAMPLE OF RANDOM WALK

BERNOULLI PROCESS



initial condition: $x_{n_0}[0] = 0$

RANDOM WALK



RANDOM WALK

PROBABILISTIC DESCRIPTION

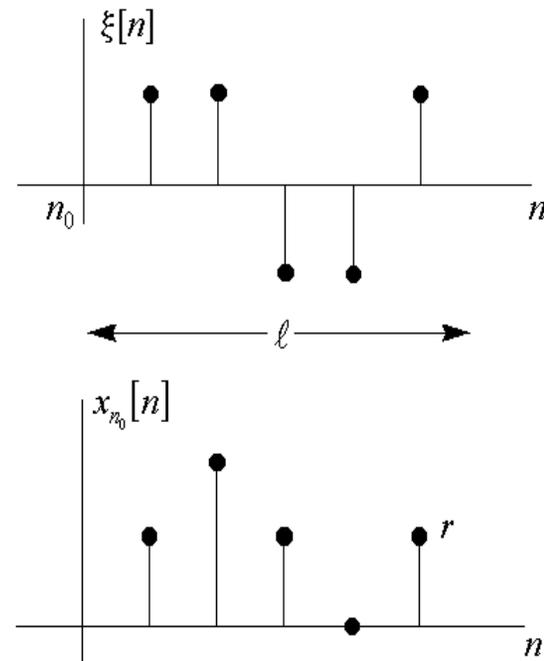
Define $\ell = n - n_0$
(relative time from start)

Suppose there are q $+1$'s
and $l - q$ -1 's

then $r = q - (l - q) = 2q - l$

and r can have values:

$-l, -l + 2, -l + 4, \dots, l - 2, l$



RANDOM WALK (cont'd.)

Value of the random walk at $n = n_0 + l$ is $r = 2q - l$

Number of +1's:

$$q = \frac{l + r}{2}$$

Number of -1's:

$$l - q = \frac{l - r}{2}$$

DISTRIBUTION

$$\Pr[x_{n_0}[n_0 + l] = r] = \binom{l}{q} P^q (1 - P)^{l - q} = \binom{l}{\frac{l+r}{2}} P^{\frac{l+r}{2}} (1 - P)^{\frac{l-r}{2}}$$

$$r = -l, -l + 2, \dots, l - 2, l$$

MOMENTS OF RANDOM WALK

MEAN

$$\begin{aligned}\mathcal{E}\{x_{n_0}[n]\} &= \mathcal{E}\left\{\sum_{k=n_0+1}^n \xi[k]\right\} = \sum_{k=n_0+1}^n \mathcal{E}\{\xi[k]\} \\ &= (n - n_0) \cdot \mathcal{E}\{\xi[k]\} = (2P - 1)(n - n_0)\end{aligned}$$

VARIANCE

$$\begin{aligned}\text{Var}[x_{n_0}[n]] &= \sum_{k=n_0+1}^n \text{Var}[\xi[k]] \\ &= (n - n_0) \text{Var}[\xi[k]] = 4P(1 - P)(n - n_0)\end{aligned}$$

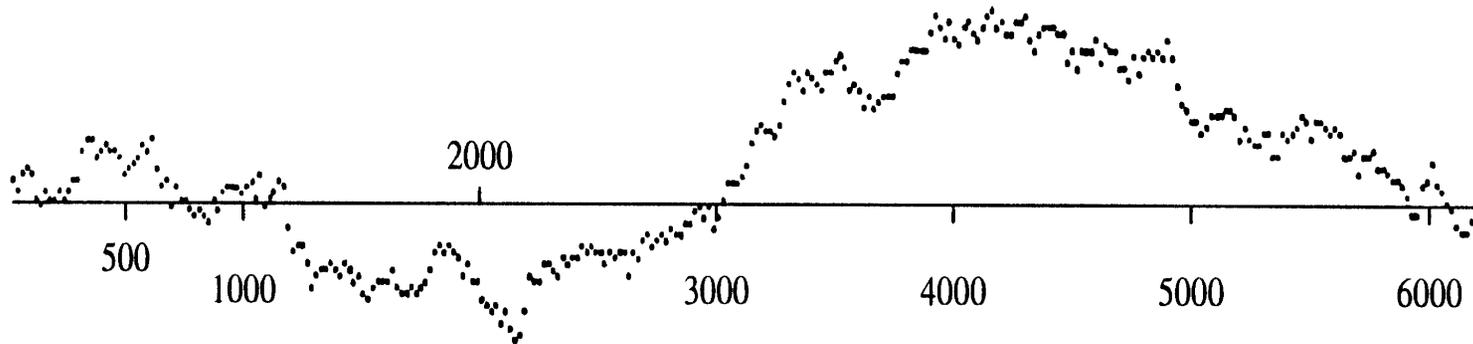
RANDOM WALK

SUMMARY

	Random Walk	Discrete Wiener Process
Distribution $\Pr[x[n] = r]$	$\binom{n-n_0}{\frac{n-n_0+r}{2}} P^{\frac{n-n_0+r}{2}} (1-P)^{\frac{n-n_0-r}{2}}$ $ r \leq n - n_0; \quad n - n_0 + r \text{ even}$	$\binom{n-n_0}{\frac{n-n_0+r}{2}} \left(\frac{1}{2}\right)^{n-n_0}$ $ r \leq n - n_0; \quad n - n_0 + r \text{ even}$
Mean	$(2P - 1)(n - n_0)$	0
Variance	$4P(1 - P)(n - n_0)$	$n - n_0$

RANDOM WALK: GENERAL CHARACTER

- Tends to have long runs of positive and negative values.
- Length of runs increases with increasing time, but local behavior remains the same.



PERIODIC RANDOM PROCESS (STRICT SENSE)

DEFINITION

$$f_{x[n_0], x[n_1], \dots, x[n_L]} = f_{x[n_0+k_0P], x[n_1+k_1P], \dots, x[n_L+k_LP]}$$

For some (\exists) P and for all (\forall) choices of the n_i , k_i , and L .

- If the condition is true only for $k_0 = k_1 = \dots = k_L = k$ then the process is called cyclostationary.

PERIODIC RANDOM PROCESS: EXAMPLES

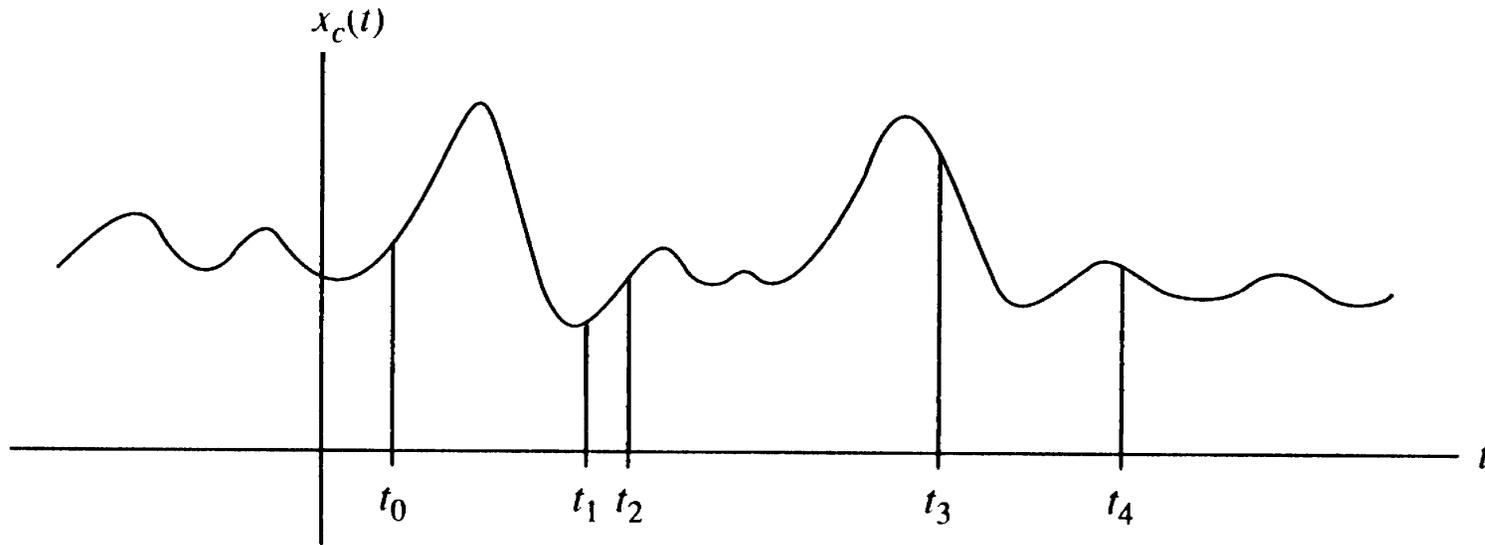
1. $x[n] = A \cos(\omega_0 n + \phi)$ A, ϕ are real random variables
2. $x[n] = \sum_i A_i \cos(\omega_i + \phi_i)$ A_i, ϕ_i are real random variables
3. $x[n] = \sum_i A_i e^{j\omega_i n}$ $A_i = |A_i| e^{j\phi_i}$ and $|A_i|, \phi_i$ are
real random variables (A_i is a complex random variable)

- ω_i is assumed to be of the form

$$\omega_i = \frac{K_i}{P_i} 2\pi \quad \text{with} \quad K_i \text{ and } P_i \text{ integers}$$

Otherwise the process is called almost periodic.

CONTINUOUS RANDOM PROCESS



- Every sample $x_c(t_i)$ is a random variable.
- Complete statistical description requires being able to specify *every* joint density.

PROPERTIES OF CONTINUOUS RANDOM PROCESSES

STATIONARITY

Distribution/density function depend on only spacing between samples.

ERGODICITY

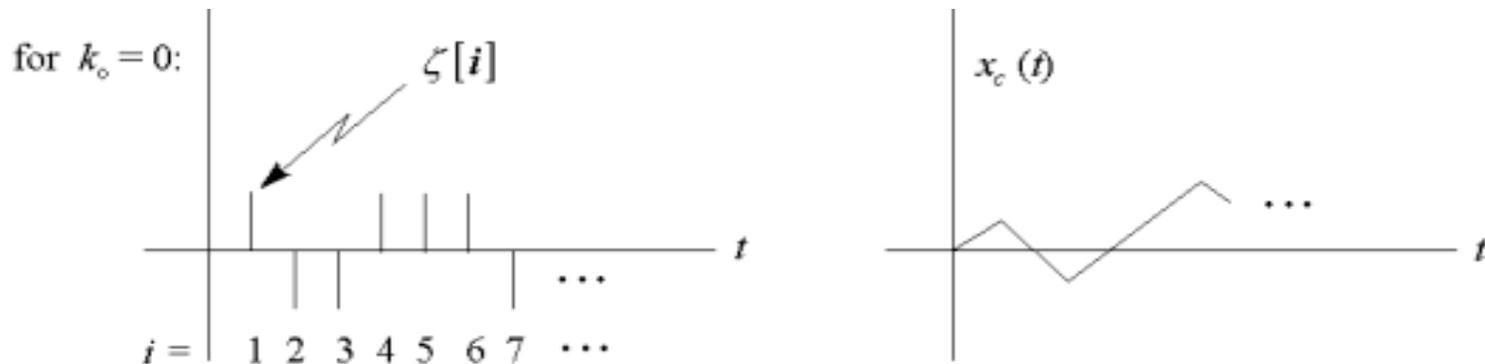
Signal (time) averages \doteq ensemble averages.

Signal average:

$$\langle x_c(t) \rangle = \lim_{\gamma \rightarrow \infty} \frac{1}{2\gamma} \int_{-\gamma}^{\gamma} x_c(t) dt$$

CONTINUOUS WIENER PROCESS (BROWNIAN MOTION PROCESS)

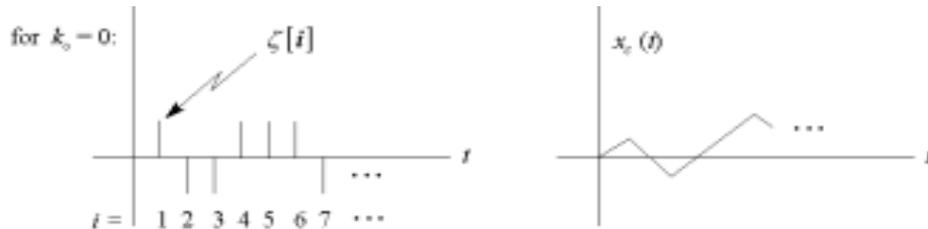
Define $x_c(k\Delta t) = \sum_{i=k_0+1}^k s\zeta[i]$ with $s \rightarrow 0, \Delta t \rightarrow 0, t = k\Delta t$



$\zeta[i]$: a binary white noise process

$$\mathcal{E}\{x_c(k\Delta t)\} = 0 \quad \text{Var}[x_c(k\Delta t)] = s^2(k - k_0) = \frac{s^2(t - t_0)}{\Delta t}$$

WIENER PROCESS (cont'd.)



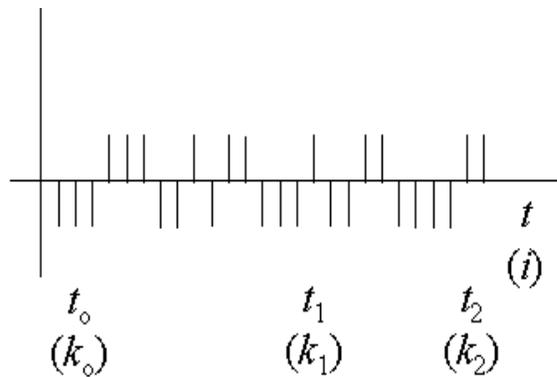
$$\mathcal{E}\{x_c(t)\} = 0 \quad \text{Var}[x_c(t)] = \frac{s^2(t - t_0)}{\Delta t}$$

Let $\Delta t \rightarrow 0$ and $s \rightarrow 0$ such that $\frac{s^2}{\Delta t} \rightarrow \nu_0$ (a constant).

Then $\text{Var}[x_c(t)] \rightarrow \nu_0(t - t_0)$ and by the central limit theorem:

$$f_{x_c(t)}(x) = \frac{1}{\sqrt{2\pi\nu_0(t - t_0)}} e^{-\frac{x^2}{2\nu_0(t - t_0)}} \quad (x_c \text{ is Gaussian})$$

JOINT DENSITY (TWO SAMPLES)



$$x_c(t_2) = \underbrace{\sum_{i=k_0+1}^{k_1} s\zeta[i]}_{x_c(t_1)} + \underbrace{\sum_{i=k_1+1}^{k_2} s\zeta[i]}_u$$

$$\downarrow \qquad \qquad \downarrow \qquad \qquad \downarrow$$

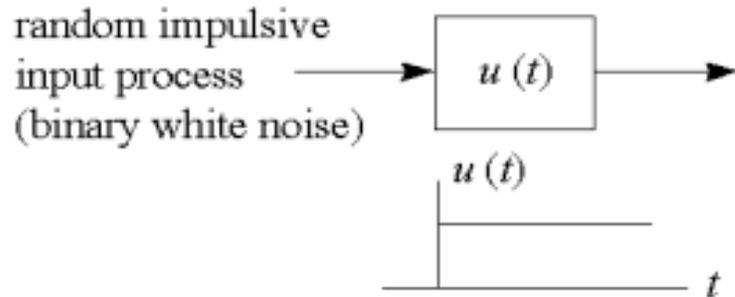
$$x_2 = x_1 + u$$

$$\begin{bmatrix} x_1 \\ x_2 \end{bmatrix} = \begin{bmatrix} 1 & 0 \\ 1 & 1 \end{bmatrix} \begin{bmatrix} x_1 \\ u \end{bmatrix} \Rightarrow x_1, x_2 \text{ jointly Gaussian}$$

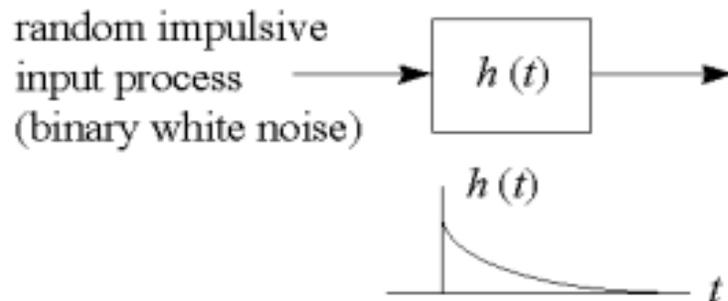
- Argument extends to any number of samples.

We say the process is Gaussian.

CONTINUOUS GAUSSIAN PROCESS



Output is a Wiener process (non-stationary, variance increases linearly with time).



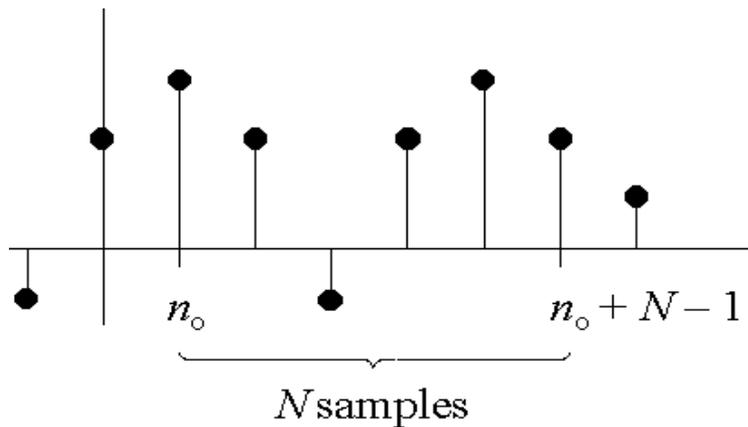
Output is a Gaussian process (stationary, variance is constant) (see Problem 3.25)

COMPLEX GAUSSIAN PROCESS

- Complex Gaussian processes occur when a random impulsive input is applied to a bandpass filter, and the resulting output process is represented at baseband (see text, Appendix B).
- A complex Gaussian random process has real and imaginary parts which are
 - jointly Gaussian.
 - identically distributed.

DISCRETE GAUSSIAN PROCESS

A discrete random process is Gaussian if any set of N samples are jointly Gaussian.



$$\mathbf{x} = \begin{bmatrix} x[n_0] \\ x[n_0 + 1] \\ \vdots \\ x[n_0 + N - 1] \end{bmatrix}$$

$$f_{\mathbf{x}}(\mathbf{x}) = \frac{1}{(2\pi)^{\frac{N}{2}} |\mathbf{C}_{\mathbf{x}}|^{\frac{1}{2}}} e^{-\frac{1}{2}(\mathbf{x} - \mathbf{m}_{\mathbf{x}})^T \mathbf{C}_{\mathbf{x}}^{-1} (\mathbf{x} - \mathbf{m}_{\mathbf{x}})} \quad (\text{real case})$$

$$f_{\mathbf{x}}(\mathbf{x}) = \frac{1}{\pi^N |\mathbf{C}_{\mathbf{x}}|} e^{-(\mathbf{x} - \mathbf{m}_{\mathbf{x}})^* T \mathbf{C}_{\mathbf{x}}^{-1} (\mathbf{x} - \mathbf{m}_{\mathbf{x}})} \quad (\text{complex case})$$

TRANSFORMATION BY LINEAR SYSTEMS

- A linear transformation of a Gaussian process produces another Gaussian process.

