

IV.b Detection of Dynamic Signals in White Gaussian Noise

- ❖ Binary Detection Problem
- ❖ Noise Effects
- ❖ Sampling Interval Restriction and pdf Computations
- ❖ Performance Analysis for Communication Receiver
- ❖ Examples to Communications and Radar
- ❖ Matched Filters
 - Definition
 - Matched filter used in detection
 - Extension to M-ary communications systems
- ❖ Sampled Data Approach
 - Definition
 - Independent noise samples
 - Gaussian signals
- ❖ **Detection of Signals With Random Parameters**
 - Signals with random phase
 - Signals with random phase & amplitude
 - Signals with random frequency
- ❖ **Multiple Pulse Detection**
 - Known signal characteristics
 - Signal with unknown phase

❖ Detection of Signals with Random Parameters

- Fact: In practical applications not all signal characteristics may be known.
 - └→ phase, amplitude, frequency may be random
- Assume *a priori* pdfs are known.

(1) Signals with random phase

- Problem to solve

$$H_0: s_0(t) = 0$$

$$H_1: s_1(t) = A \sin(\omega_c t + \theta)$$

$$0 \leq t \leq T$$

- Problem to solve at the receiver

$$H_0: y(t) = n(t)$$

$$H_1: y(t) = A \sin(\omega_c t + \theta) + n(t)$$

$$0 \leq t \leq T$$

- How to solve

└→ use composite hypothesis testing

$$\Lambda_\theta(y) =$$

$$\Rightarrow \Lambda(y) =$$

– How to define pdfs

- * If we have m samples for data sampled at Δt

$$f_0(y_i) =$$

$$f_0(\underline{y}) =$$

- * As $m \rightarrow +\infty$ and $\Delta t \rightarrow 0$

$$f_0(y) =$$

$$f_1(y) =$$

$$\Lambda_\theta(y) =$$

$$\Lambda(y) =$$

$$\exp\left(\frac{-A^2T}{2N_0}\right) \frac{1}{2\pi} \int_0^{2\pi} \exp\left(\frac{2A}{N_0}q \cos(\theta_0 - \theta)\right) d\theta$$

use the fact that $\frac{1}{2\pi} \int_0^{2\pi} \exp(x \cos(\theta + \alpha)) d\theta = I_0(x)$

where $I_0(x)$: modified Bessel function of the first kind
and zero-th order

$$\implies \frac{1}{2\pi} \int_0^{2\pi} \exp\left(\frac{2A}{N_0}q \cos(\theta_0 - \theta)\right) d\theta = I_0\left(\frac{2Aq}{N_0}\right)$$

$$\implies \Lambda(y) = \exp\left(\frac{-A^2T}{2N_0}\right) I_0\left(\frac{2Aq}{N_0}\right) > \lambda_0$$

$$\implies I_0\left(\frac{2Aq}{N_0}\right) < \lambda_0 \exp\left(\frac{A^2T}{2N_0}\right)$$

$$\implies q > \eta_0 \quad \text{or} \quad q^2 < \eta_1$$

- ***To compute the actual decision rule:***

1) for a specified λ_0 solve for η_0 as:

$$\lambda_0 = \exp\left(\frac{-A^2 T}{2N_0}\right) I_0\left(\frac{2A\eta_0}{N_0}\right)$$

2) for a NP test, threshold η_0 or η_1 determined from the P_{FA}

- ***How to compute q:***

Note that expressions derived involve $q\cos(\theta_0)$ and $q\sin(\theta_0)$, one can get rid of the trigonometric expressions by computing:

$$q\cos^2(\theta_0) + q\sin^2(\theta_0) = q^2$$

- ***Simplification for high and low SNR levels***

$$\text{For low SNR: } I_0\left(\frac{2Aq}{N_0}\right) \approx 1 + \left(\frac{Aq}{N_0}\right)^2$$

$$\implies \ln\left(I_0\left(\frac{2Aq}{N_0}\right)\right) \approx \ln\left(1 + \left(\frac{Aq}{N_0}\right)^2\right) \approx \left(\frac{Aq}{N_0}\right)^2$$

$$\text{For high SNR: } I_0\left(\frac{2Aq}{N_0}\right) \approx \frac{\exp\left(\frac{2Aq}{N_0}\right)}{\left(4\pi Aq / N_0\right)^{1/2}}$$

$$\implies \ln\left(I_0\left(\frac{2Aq}{N_0}\right)\right) \approx 2Aq / N_0 - \frac{1}{2} \ln\left(\frac{4\pi Aq}{N_0}\right) \approx \frac{2Aq}{N_0}$$

- ***How to apply the above simplifications:***

$$I_0\left(\frac{2Aq}{N_0}\right) > \lambda_0 \exp\left(\frac{A^2 T}{2N_0}\right)$$

$$\implies \ln\left(I_0\left(\frac{2Aq}{N_0}\right)\right) > \ln(\lambda_0) + \left(\frac{A^2 T}{2N_0}\right)$$

at low SNR levels:

$$\left(\frac{Aq}{N_0}\right)^2 > \ln(\lambda_0) + \left(\frac{A^2 T}{2N_0}\right) = \gamma$$

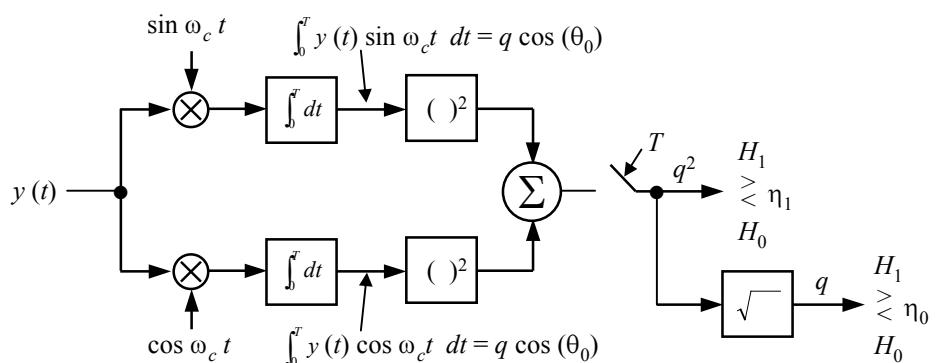
$$\implies \boxed{q^2 > \left(\frac{N_0}{A}\right)^2 \gamma}$$

- How do we implement this detector ?

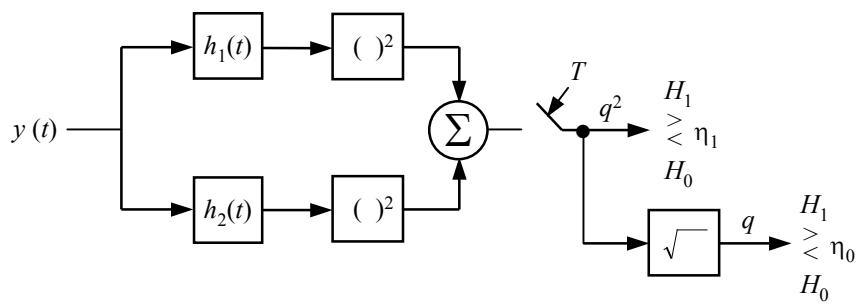
1) correlator implementation

$$\Lambda(y) = \exp\left(\frac{-A^2 T}{2N_0}\right) \frac{1}{2\pi} \int_0^{2\pi} \exp\left(\frac{2A}{N_0} \left[\int_0^T \sin(\omega_c t) y(t) dt \cos(\theta) + \dots \right.\right.$$

$$\left. \left. + \int_0^T \cos(\omega_c t) y(t) dt \sin(\theta) \right] \right)$$



3) matched filter implementation



2) incoherent matched filter implementation

Review: Complex/real signal envelope definitions

Assume $f(t)$ is defined as:

$$f(t) = a(t) \cos(\omega_c t + \phi(t))$$

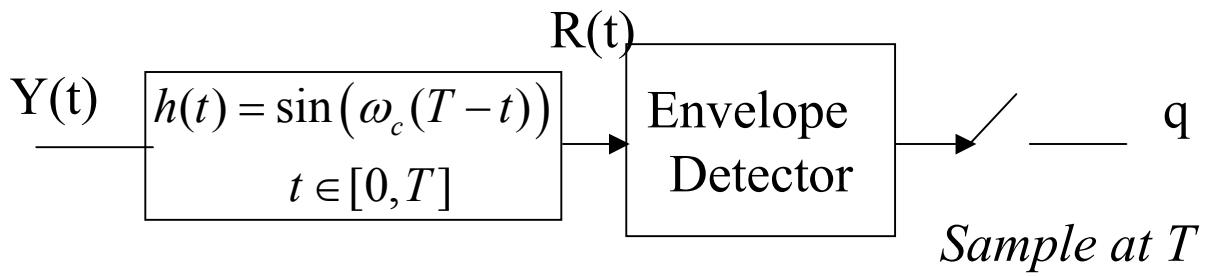
$$= \operatorname{Re} \left[\tilde{f}(t) \exp(j\omega_c t) \right],$$

$$\text{where } \tilde{f}(t) = a(t) \exp(j\phi(t))$$

Complex envelope

$$= a(t) + jb(t)$$

Real envelope: $|\tilde{f}(t)| = \sqrt{a^2(t) + b^2(t)}$



$$R(t) =$$

Real envelope of $R(t)$:

$$E(t) =$$

• Receiver Performance

- Need to derive ROC curves to get an idea of the performances
- ROC curves require to get the pdf of q
- Define: $x = \int_0^T y(t) \sin(\omega_c t) dt; z = \int_0^T y(t) \cos(\omega_c t) dt$
- Recall: $q = (x^2 + z^2)^{1/2}$
- Note: $x = q \cos(\alpha); z = q \sin(\alpha)$ may be defined where
 $\alpha = \tan^{-1}(z/x)$

* Under H_1 :

$n(t)$ is Gaussian $\Rightarrow x$ and z are Gaussian

$$f_1(x, z | \theta) = f_1(x | \theta) f_1(z | \theta), \quad \text{why?}$$

$$f_1(x, z | \theta) = \left\{ \frac{1}{\sigma_x \sqrt{2\pi}} \exp\left(\frac{-1}{2\sigma_x^2} (x - m_x)^2 \right) \right\} \cdot \\ \left\{ \frac{1}{\sigma_z \sqrt{2\pi}} \exp\left(\frac{-1}{2\sigma_z^2} (z - m_z)^2 \right) \right\}$$

- Need to compute mean and variance for H_0 and H_1

A) mean

$$E\{x | \theta\}_{H_1} =$$

$$E\{z | \theta\}_{H_1} =$$

B) Variance

$$Var \{x | \theta\}_{H_1} = E \left\{ \left(x - E \{x | \theta\}_{H_1} \right)^2 \right\}$$

C) Resulting pdf expression

$$f_1(x, z | \theta) = \frac{1}{\sigma^2 2\pi} \exp \left(-\frac{1}{2\sigma^2} \left[\left(x - \frac{AT}{2} \cos(\theta) \right)^2 + \left(z - \frac{AT}{2} \sin(\theta) \right)^2 \right] \right)$$

using the transformation: $x = q \cos(\alpha), z = q \sin(\alpha), \alpha = \tan^{-1}(z/x)$

$$f_1(q, \alpha | \theta) = \frac{q}{\sigma^2} \exp \left(-\frac{1}{2\sigma^2} \left[\left(\frac{AT}{2} \right)^2 + q^2 - ATq \cos(\theta - \alpha) \right] \right)$$

$$\begin{aligned} \implies f_1(q | \theta) &= \int_0^{2\pi} f_1(q, \alpha | \theta) d\alpha = \\ &= \frac{q}{\sigma^2} \exp \left(-\frac{1}{2\sigma^2} \left[\left(\frac{AT}{2} \right)^2 + q^2 \right] \right). \\ &\quad \int_0^{2\pi} \frac{1}{2\pi} \exp \left(\frac{ATq \cos(\theta - \alpha)}{2\sigma^2} \right) d\alpha \end{aligned}$$

\implies

$$f_1(q | \theta) = \frac{q}{\sigma^2 2\pi} \exp \left(-\frac{1}{2\sigma^2} \left[\left(\frac{AT}{2} \right)^2 + q^2 \right] \right) I_0 \left(\frac{ATq}{2\sigma^2} \right)$$

$$\implies f_1(q) = \int_0^{2\pi} \frac{1}{2\pi} f_1(q | \theta) d\theta$$

$$f_1(q) = \frac{q}{\sigma^2} \exp \left(-\frac{1}{2\sigma^2} \left[\left(\frac{AT}{2} \right)^2 + q^2 \right] \right) I_0 \left(\frac{ATq}{2\sigma^2} \right) (1/2\pi \times 2\pi)$$

- **Pdf under H_0**

$$f_1(q) = \frac{q}{\sigma^2} \exp\left(-\frac{1}{2\sigma^2} \left[\left(\frac{AT}{2}\right)^2 + q^2 \right]\right) I_0\left(\frac{ATq}{2\sigma^2}\right)$$

Note: Under H_0 , $A=0$

$$f_0(q) = \frac{q}{\sigma^2} \exp\left(-\frac{q^2}{2\sigma^2}\right)$$

- P_{fa} and P_d

$$\begin{aligned}
 P_{fa} &= \int_{\eta}^{\infty} f_0(q) dq = \int_{\eta}^{\infty} \frac{q}{\sigma^2} \exp\left(\frac{-q^2}{2\sigma^2}\right) dq \\
 &= \exp\left(-\eta^2 / 2\sigma^2\right)
 \end{aligned}$$

$$\begin{aligned}
 P_d &= \int_{\eta}^{\infty} f_1(q) dq \\
 &= \int_{\eta}^{\infty} \frac{q}{\sigma^2} \exp\left(-\frac{1}{2\sigma^2} \left[\left(\frac{AT}{2}\right)^2 + q^2 \right]\right) I_0\left(\frac{ATq}{2\sigma^2}\right) dq
 \end{aligned}$$

doing the changes of variable:

$$v = q/\sigma,$$

$$\begin{aligned}
 \left(AT/2\right)^2 / 2\sigma^2 &= (A^2 T / 2)(T / 4\sigma^2) \\
 &= E / N_0
 \end{aligned}$$

$$\alpha^2 = 2E / N_0$$

$$\Rightarrow P_d = \int_{\eta/\sigma}^{\infty} v \exp\left(\frac{v^2 + \alpha^2}{-2}\right) I_0(\alpha v) dv$$

- ROC Curves

(2) Signals with random amplitude and phase

- Need to average effects of all random parameters.
 - random parameters shown in $f_1(y)$ only

$$\frac{\int_{\varphi=(A,\theta)} f_1(y \mid \varphi) f_A(A) f_\theta(\theta) d\varphi}{f_0(y)} > \lambda_0$$

Recall:

$$\Lambda(y \mid A) = \exp\left(\frac{-A^2 T}{2N_0}\right) I_0\left(\frac{2Aq}{N_0}\right)$$

Assume $f_A(A)$ is Rayleigh distributed

$$f_A(A) = \frac{A}{A_0^2} \exp\left(\frac{-A^2}{2A_0^2}\right) U(A)$$

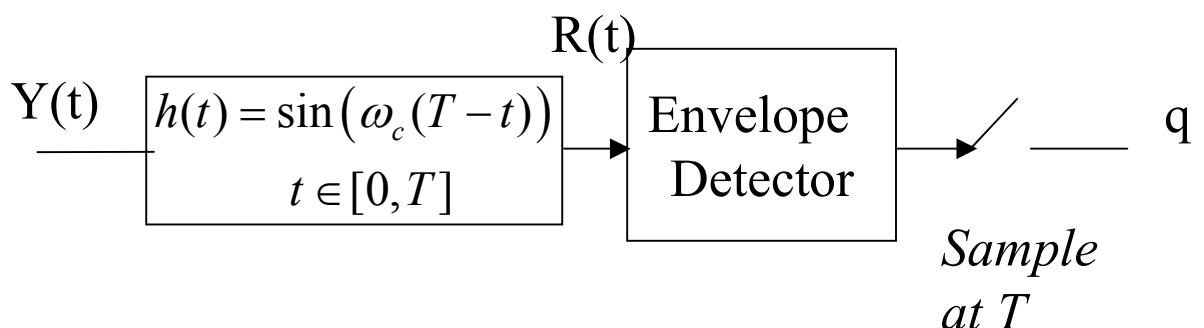
$$\Lambda(y) = \int_0^\infty \exp\left(\frac{-A^2 T}{2N_0}\right) I_0\left(\frac{2Aq}{N_0}\right) f_A(A) dA$$

After simplifications,

$$\Lambda(y) = \frac{N_0}{N_0 + TA_0^2} \exp\left(\frac{2A_0^2 q^2}{N_0(N_0 + TA_0^2)}\right)$$

$$\Rightarrow \ln\left(\frac{N_0}{N_0 + TA_0^2}\right) + \frac{2A_0^2 q^2}{N_0(N_0 + TA_0^2)} > \ln(\lambda_0)$$

$$\Rightarrow q > \left[\left\{ \frac{N_0(N_0 + TA_0^2)}{2A_0^2 q^2} \right\} \ln\left[\frac{\lambda_0(N_0 + TA_0^2)}{N_0}\right] \right]^{1/2}$$



- ROC Curves

(3) Signals with random frequency and phase

- Problem occurs in radar (doppler shifting)
in communications (time-varying channels)
- Assume: Uniform phase, and AWGN

$$\Lambda(y | \omega) = \exp\left(\frac{-A^2 T}{2N_0}\right) I_0\left(\frac{2Aq}{N_0}\right)$$

$$\Rightarrow \Lambda(y) = \int_0^\infty \exp\left(\frac{-A^2 T}{2N_0}\right) I_0\left(\frac{2Aq}{N_0}\right) f_\omega(\omega) d\omega$$

$$\text{where } q^2 = \left[\int_0^T y(t) \sin(\omega t) dt \right]^2 + \dots$$

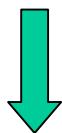
$$+ \left[\int_0^T y(t) \cos(\omega t) dt \right]^2$$

- LRT cannot be computed in a closed form solution
==> need an approximation

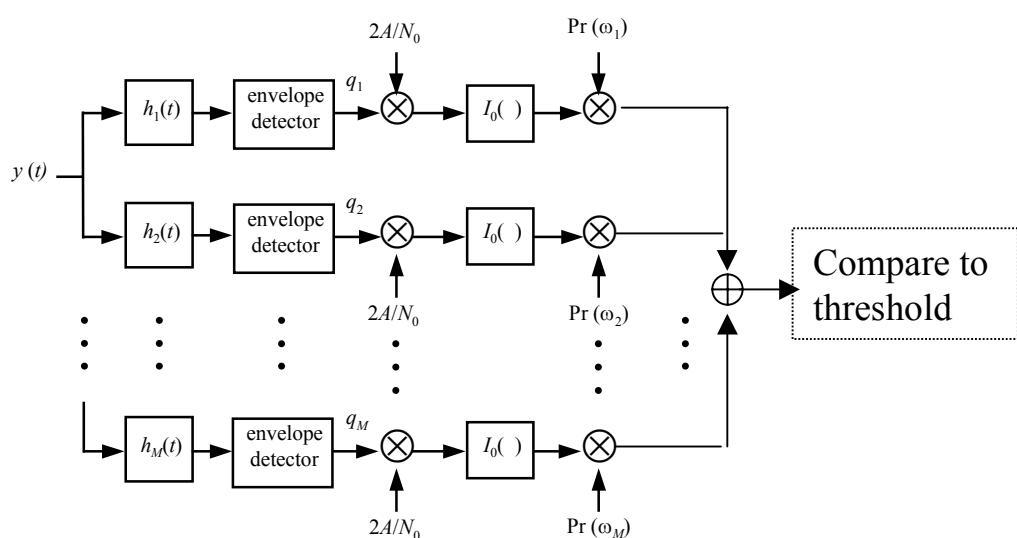
$$f_{\omega}(\omega) \simeq \sum_{i=1}^M P(\omega_i) \delta(\omega - \omega_i)$$

$$\text{with } P(\omega_i) = f_{\omega}(\omega_i) \Delta\omega$$

$$\text{and } \omega_i = \omega_1 + i\Delta\omega, i = 1, \dots, M$$



$$\begin{aligned}\Lambda(y) &= \int_{\omega_1}^{\omega_2} \Lambda(y | \omega) f_{\omega}(\omega) d\omega \\ &= \sum_{i=1}^M \Lambda(y | \omega_i) P(\omega_i)\end{aligned}$$



- Simplification for small SNR level

$$\text{Recall } I_0\left(\frac{2Aq_i}{N_0}\right) \approx 1 + \left(\frac{Aq_i}{N_0}\right)^2$$

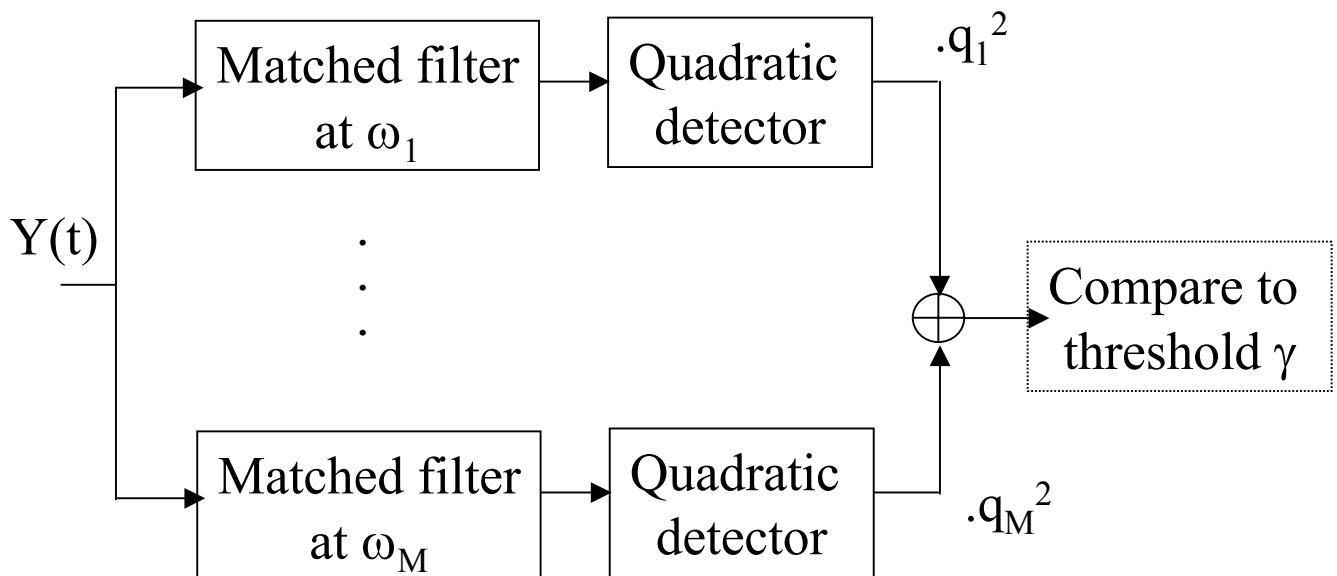
- Assume that $P(\omega_i) = 1/M$

→ $\Lambda(y) = (1/M) \sum_{i=1}^M \exp\left(-A^2 T / 2N_0\right) \left[1 + \left(Aq_i / N_0\right)^2 \right]$

- Decision rule may be expressed as:

$$\sum_{i=1}^M q_i^2 \geq \gamma$$

- Receiver



❖ Multiple Pulse Detection

- Recall: Decision made earlier based on one single pulse only.
- In practice: Multiple pulses may be available.
Ex:
 - radar: pulses received sequentially
 - communications: transmission over multiple channels

1) Known Radar Signal Case

Assume signals are completely known

$$H_0: y_i(t) = n_i(t), i=1, \dots, M$$

$$H_1: y_i(t) = s_i(t) + n_i(t),$$

Return pulse at receiver

Assume received signals are independent

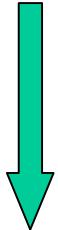
$$\Lambda(y) = \frac{f_1(y_1, \dots, y_M)}{f_0(y_1, \dots, y_M)} = \frac{f_1(y_1)f_1(y_2)\dots f_1(y_M)}{f_0(y_1)f_0(y_2)\dots f_0(y_M)}$$

$$= \prod_{i=1}^M \Lambda_i(y_i)$$

LRT for i^{th} pulse

$$f_1(y_i) = K \exp\left(-(1/N_0) \int_0^T [y_i(t) - s_i(t)]^2\right)$$

$$f_0(y_i) = K \exp\left(-(1/N_0) \int_0^T [y_i(t)]^2\right)$$



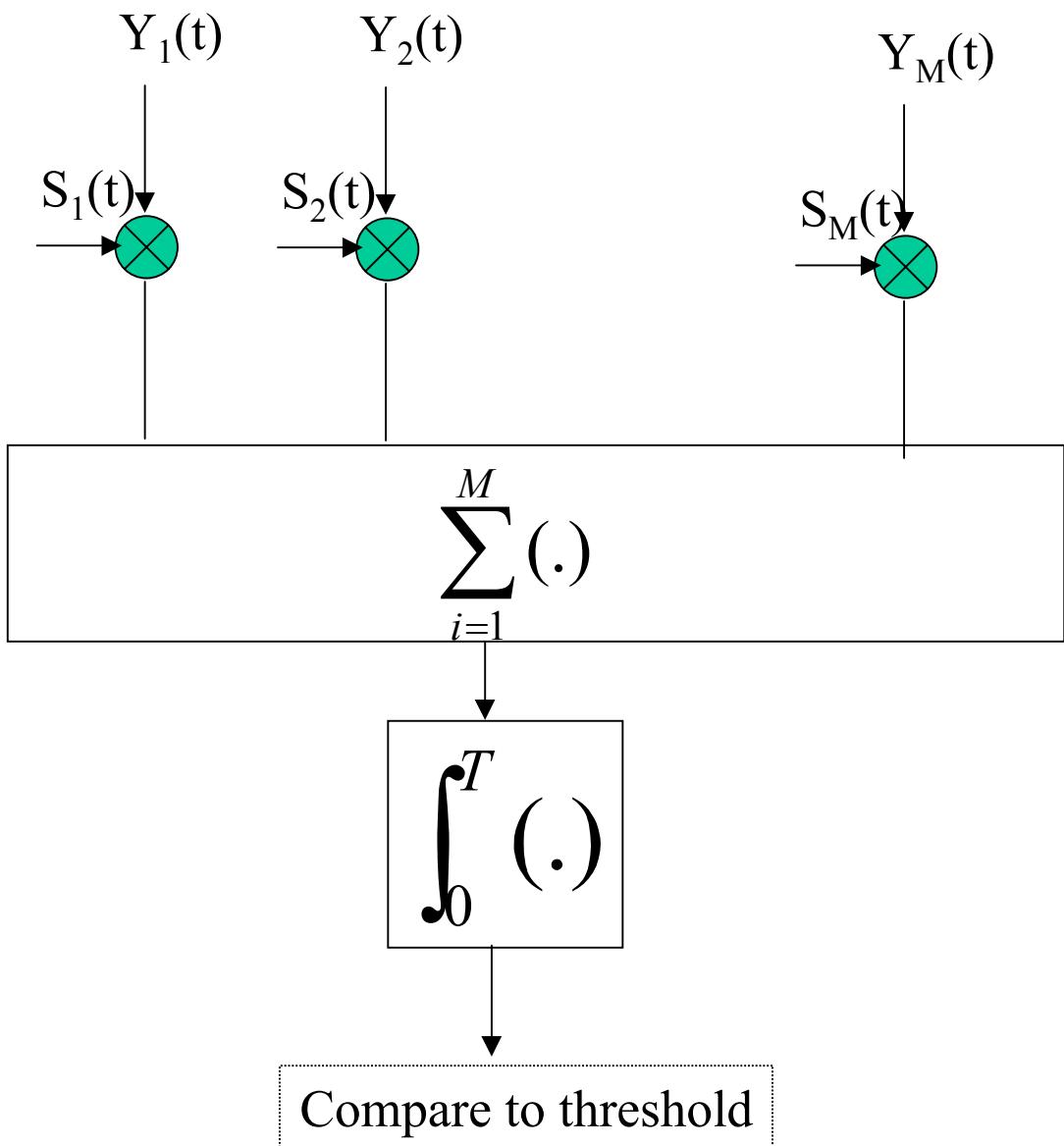
$$\Lambda_i(y_i) = \exp\left(-(1/N_0) \int_0^T s_i^2(t) dt\right) \exp\left((2/N_0) \int_0^T y_i(t) s_i(t) dt\right)$$

$$\implies \ln[\Lambda(y)] = \ln\left[\prod_{i=1}^M \Lambda_i(y_i)\right]$$

$$= -(1/N_0) \sum_{i=1}^M E_i + (2/N_0) \sum_{i=1}^M \int_0^T y_i(t) s_i(t) dt > \ln(\lambda_0)$$

$$\implies \sum_{i=1}^M \int_0^T y_i(t) s_i(t) dt < \gamma \triangleq \frac{N_0}{2} \ln(\lambda_0) + \frac{1}{2} \sum_{i=1}^M E_i$$

Conclusion: receiver structure similar to the single pulse case, except that there are now M such receivers



1) Known Signal Case - Uniform random phase

$$s_i(t) = A \sin(\omega_c t + \theta_i)$$

$$\Lambda_i(y_i) = \exp\left(\frac{-A^2 T}{2N_0}\right) I_0\left(\frac{2Aq_i}{N_0}\right)$$

where $q_i^2 = \left[\int_0^T y_i(t) \sin(\omega_c t) dt \right]^2 + \dots$

$$+ \left[\int_0^T y_i(t) \cos(\omega_c t) dt \right]^2$$

$$\begin{aligned} \Lambda(y) &= \frac{f_1(y_1, \dots, y_M)}{f_0(y_1, \dots, y_M)} = \frac{f_1(y_1)f_1(y_2)\dots f_1(y_M)}{f_0(y_1)f_0(y_2)\dots f_0(y_M)} \\ &= \prod_{i=1}^M \Lambda_i(y_i) \end{aligned}$$

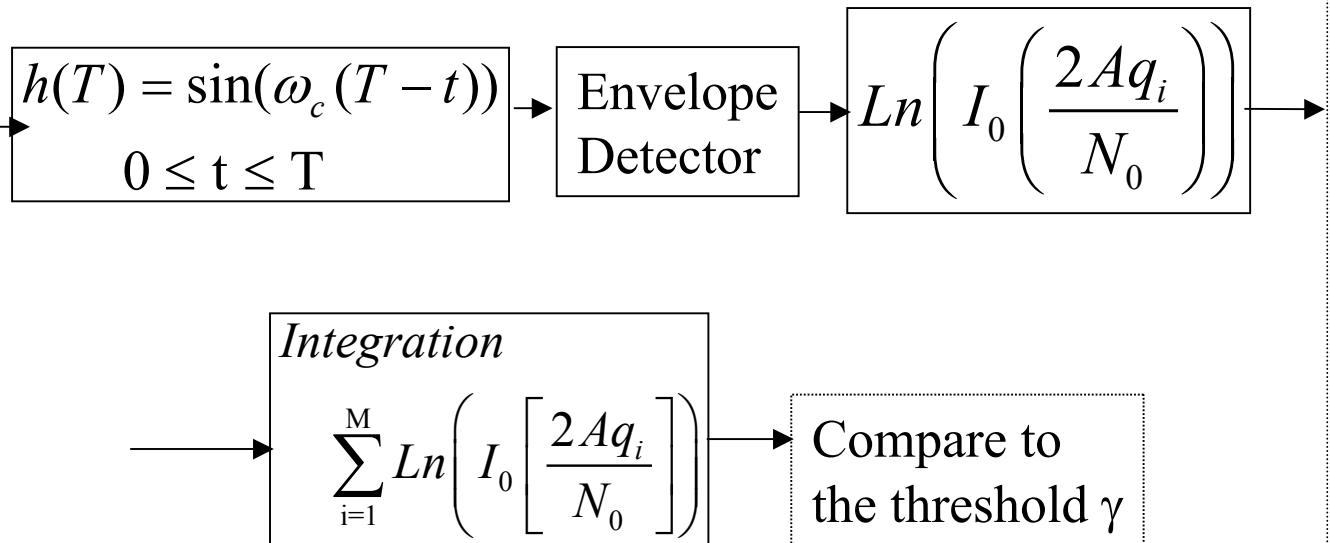
==>

$$\ln[\Lambda(y)] = -\frac{MA^2 T}{2N_0} + \sum_{i=1}^M \ln\left[I_0\left(\frac{2Aq_i}{N_0}\right)\right]$$

==>

$$\sum_{i=1}^M \ln\left[I_0\left(\frac{2Aq_i}{N_0}\right)\right] > \gamma \triangleq \ln(\lambda_0) + \frac{MA^2 T}{2N_0}$$

$$\sum_{i=1}^M I_0 \left(\frac{2Aq_i}{N_0} \right) > \gamma \triangleq \ln(\lambda_0) + \frac{MA^2T}{2N_0}$$



Incoherent Detector for a train of M pulses

- Simplification for small SNR levels

- Recall: $I_0\left(\frac{2Aq_i}{N_0}\right) \approx 1 + \left(\frac{Aq_i}{N_0}\right)^2$

$$\implies \ln\left(I_0\left(\frac{2Aq_i}{N_0}\right)\right) \approx \ln\left(1 + \left(\frac{Aq_i}{N_0}\right)^2\right) \approx \left(\frac{Aq_i}{N_0}\right)^2$$

- Decision rule:

$$\sum_{i=1}^M \ln\left(I_0\left(\frac{2Aq_i}{N_0}\right)\right) > \gamma \triangleq \ln(\lambda_0) + \frac{MA^2T}{2N_0}$$

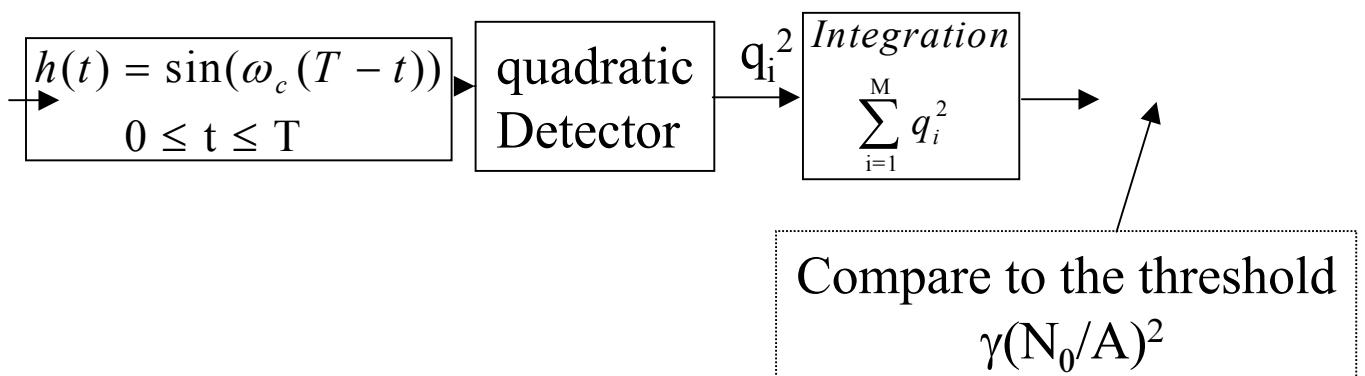
\implies

$$\sum_{i=1}^M \left(\frac{Aq_i}{N_0}\right)^2 > \gamma$$

\implies

$$\sum_{i=1}^M q_i^2 > \left(\frac{N_0}{A}\right)^2 \gamma$$

- Simplified Receiver



- Simplification for high SNR levels

- Recall:

$$I_0\left(\frac{2Aq_i}{N_0}\right) \approx \frac{\exp(2Aq_i / N_0)}{(4\pi Aq_i / N_0)^{1/2}}$$

$$\Rightarrow \ln\left(I_0\left(\frac{2Aq_i}{N_0}\right)\right) \approx -\frac{1}{2} \ln(4\pi Aq_i / N_0) + \frac{2Aq_i}{N_0}$$

- Decision rule:

$$\sum_{i=1}^M \ln\left(I_0\left(\frac{2Aq_i}{N_0}\right)\right) > \gamma \triangleq \ln(\lambda_0) + \frac{MA^2T}{2N_0}$$

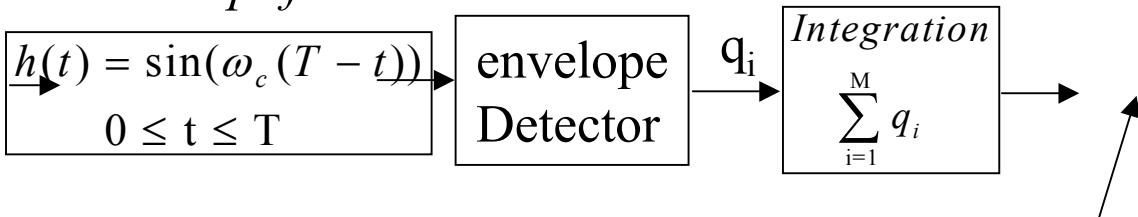
\Rightarrow

$$\sum_{i=1}^M \frac{2Aq_i}{N_0} > \gamma$$

\Rightarrow

$$\sum_{i=1}^M q_i > \frac{N_0}{2A} \gamma$$

- Simplified Receiver



Compare to the threshold
 $\gamma N_0 / (2A)$